

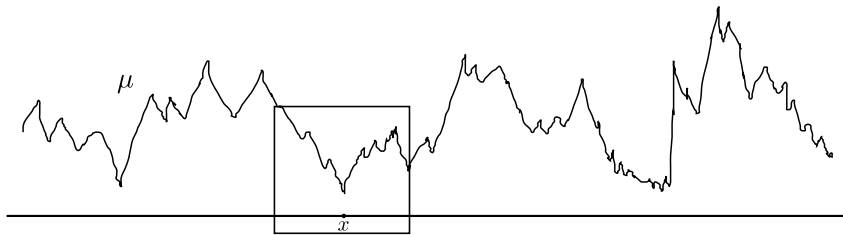
Typical tangent measures

Tuomas Sahlsten

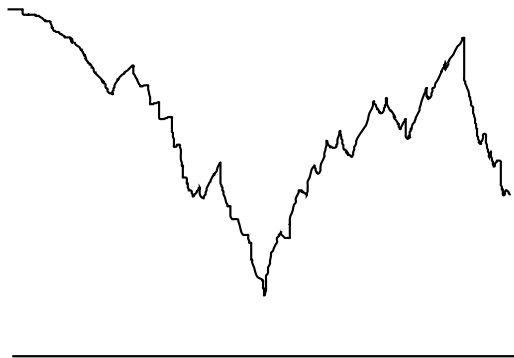
Department of Mathematics and Statistics
University of Helsinki, Finland

ETDS workshop, University of Warwick
16.4.2012

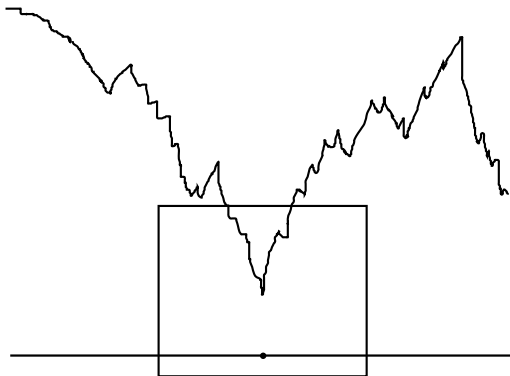
Pick a point $x \in \mathbb{R}$ and take a “photograph” of μ near x :



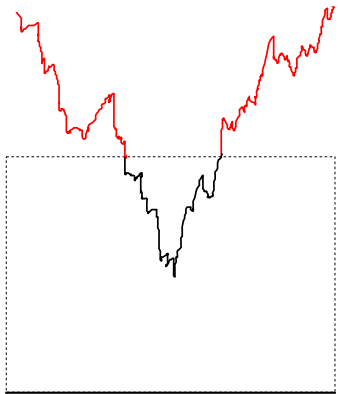
We will see something like this:



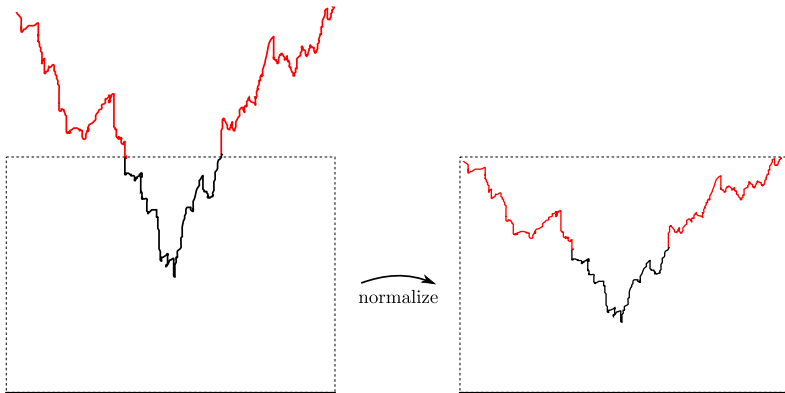
Now take another shot at an even smaller scale:



The photo is now out of the frame:



We have to “photoshop” slightly to fit the picture into the frames:

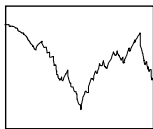


We can continue taking shots of the measure μ along scales

$$r_1 > r_2 > r_3 > \dots$$

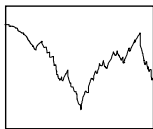
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r_1

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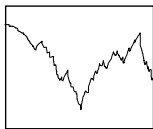


r_1



r_2

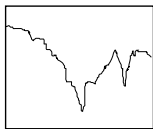
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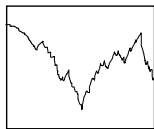


r_2



r_3

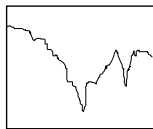
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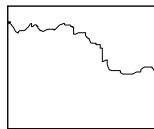
r_1



r_2

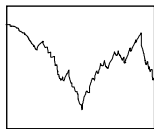


r_3



r_4

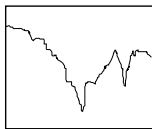
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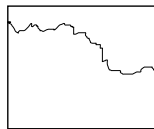
r_1



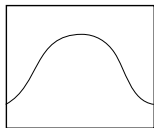
r_2



r_3

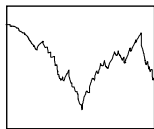


r_4



r_5

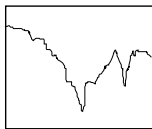
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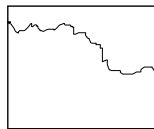
r_1



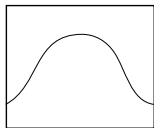
r_2



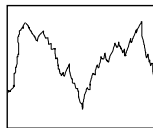
r_3



r_4

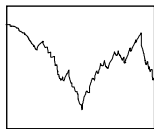


r_5



r_6

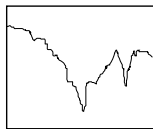
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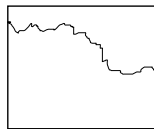
r_1



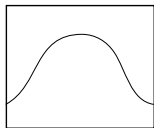
r_2



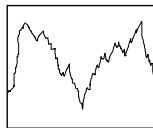
r_3



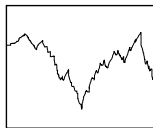
r_4



r_5

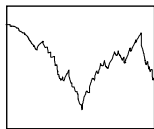


r_6



r_7

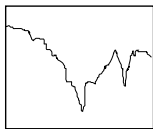
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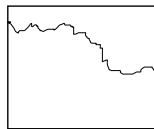
r_1



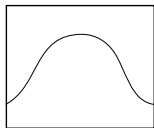
r_2



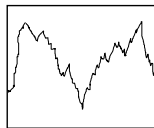
r_3



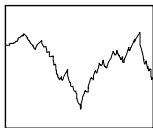
r_4



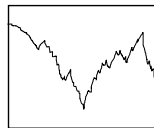
r_5



r_6

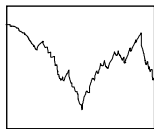


r_7



r_8

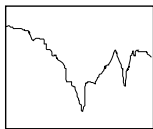
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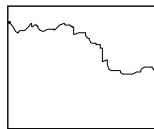
r_1



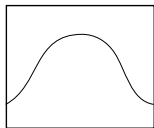
r_2



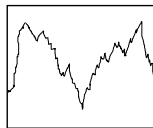
r_3



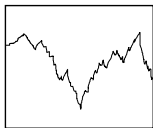
r_4



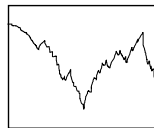
r_5



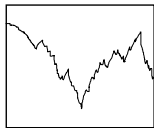
r_6



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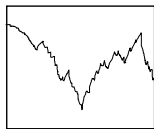


r_8



r_9

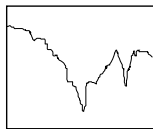
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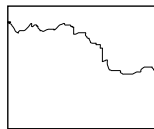
r_1



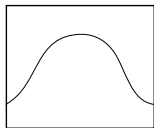
r_2



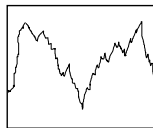
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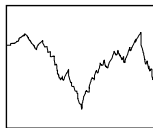
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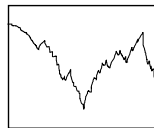
r_5



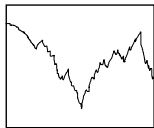
r_6



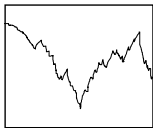
r_7



r_8

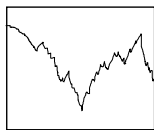


r_9



r_i

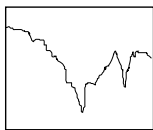
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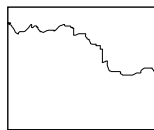
r_1



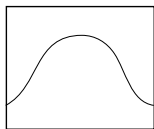
r_2



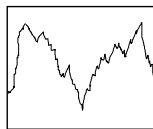
r_3



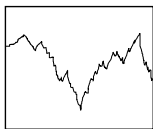
r_4



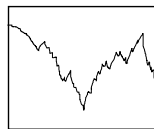
r_5



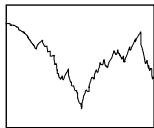
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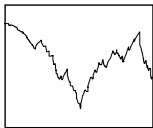
r_7



r_8



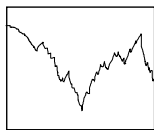
r_9



r_i

weakly
 $\xrightarrow{i \rightarrow \infty}$

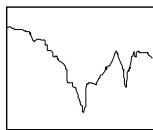
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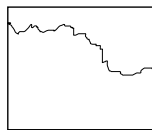
r_1



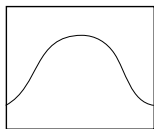
r_2



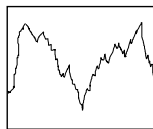
r_3



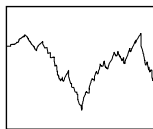
r_4



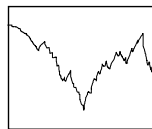
r_5



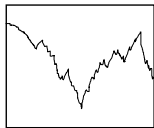
r_6



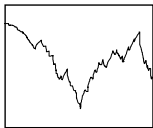
r_7



r_8

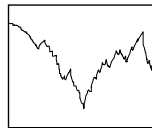


r_9



r_i

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tangent measure ν .

Tangent measures

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$$c_i T_{x, r_i} \# \mu \rightarrow \nu \quad \text{as } i \rightarrow \infty.$$

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Here $T_{x, r} : \mathbb{R}^d \rightarrow \mathbb{R}^d$ is the affine homothety that maps the ball $B(x, r)$ onto the unit ball $B(0, 1)$.

Baire category

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Let X be a complete metric space (such as \mathcal{M}). A **typical** $x \in X$ satisfies a property P of points $x \in X$ if the set

$$\{x \in X : x \text{ does not satisfy } P\}$$

is **meagre** in X , that is, it is a countable union of sets $E \subset X$ with

$$\text{int } \overline{E} = \emptyset.$$

Tangent measures of typical measures

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The set of tangent measures can be very rich:

Theorem (O'Neil, 1995)

There exists $\mu \in \mathcal{M}$ such that $\text{Tan}(\mu, x) = \mathcal{M} \setminus \{0\}$ at μ almost every $x \in \mathbb{R}^d$.

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In fact, such richness is typical:

Theorem

A typical $\mu \in \mathcal{M}$ satisfies $\text{Tan}(\mu, x) = \mathcal{M} \setminus \{0\}$ at μ almost every $x \in \mathbb{R}^d$.

Sharpness

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What about extending the result to hold at *every* point $x \in \mathbb{R}^d$?

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Not possible, since:

Proposition

For any $\mu \in \mathcal{M} \setminus \{0\}$ there exists $x \in \text{spt } \mu$ such that either $\mathcal{L}^d \notin \text{Tan}(\mu, x)$ or $\mathcal{L}^d \llcorner [0, \infty)^d \notin \text{Tan}(\mu, x)$.

Here \mathcal{L}^d is the Lebesgue-measure on \mathbb{R}^d .

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Case (1): We can choose a point $x \in \text{spt } \mu$ and $\varepsilon > 0$ such that

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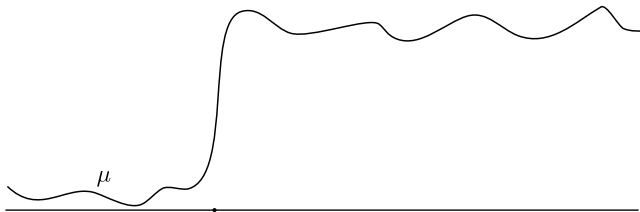
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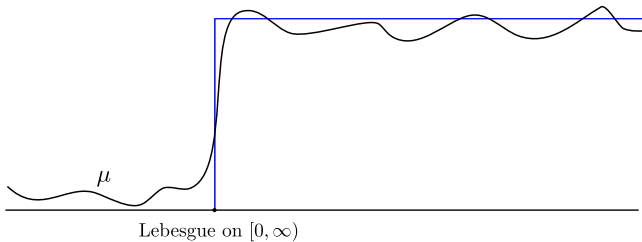
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What about case (2)?

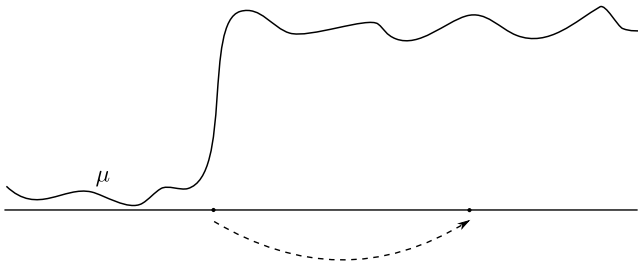
Pick a point and scale where μ looks like Lebesgue on $[0, \infty)$.



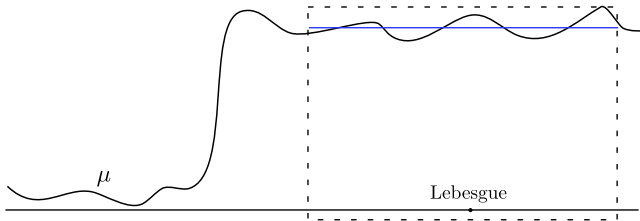
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Move a little bit to the right.



Here μ looks like Lebesgue!



Micromasures

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$$[y] = \{x = (x_1, x_2, \dots) \in I^{\mathbb{N}} : x|n := (x_1, \dots, x_n) = y\}.$$

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Definition

Let $\mu \in \mathcal{P}$ and $x \in I^{\mathbb{N}}$. A measure $\nu \in \mathcal{P}$ is a **micromasure** of μ at x if there exists $n_i \nearrow \infty$ such that

$$\mu_{x|n_i} \rightarrow \nu \quad \text{as } i \rightarrow \infty.$$

The set of all such micromeasures is denoted by $\text{micro}(\mu, x)$.

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Micromeasures are much easier to handle than tangent measures in this situation since

$$\partial[y] = \emptyset \quad \text{for any } y \in I^k, k \in \mathbb{N}.$$

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- Tangent measures/micromeasures of *prevalent* measures?
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- Tangent measure/micromasure *distributions*?
(Furstenberg, Zähle, Hochman, Shmerkin...)

References

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